# A NEW CLASS OF ROBUST POISSON RIDGE-TYPE ESTIMATOR: SIMULATION AND THEORY APPROACH

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## ABSTRACT

This study evaluates the performance of various Poisson regression estimators under conditions of multicollinearity and data contamination (outliers) using simulated data. Specifically, the mean squared errors (MSEs) of traditional estimators Robust Poisson Maximum Likelihood Estimator (RPMLE), Robust Poisson Ridge (RPR), Robust Poisson Liu (RPL), and Robust Poisson Kibria-Lukman (RPK-L) were compared with three newly proposed estimators (prop1, prop1ME, and prop1HM) across different sample sizes (n = 200, 300, 400), correlation strengths ( $\rho$  = 0.8–0.99), and contamination levels ( $\tau = 20\%$ ). Results consistently show that RPMLE yields the highest MSE, confirming its vulnerability to outliers and multicollinearity. While classical shrinkage methods perform better than RPMLE, their efficiency declines with increasing  $\rho$  and  $\tau$ . In contrast, the proposed estimators demonstrate superior robustness, with prop1HM achieving the lowest MSE across nearly all designs. Notably, prop1HM maintains its performance even under high multicollinearity and small sample sizes, highlighting its adaptability. As contamination intensifies, the performance gap between the proposed and traditional estimators widens, emphasizing the resilience of the new methods. These findings suggest that prop1HM, in particular, is a reliable and efficient alternative for Poisson regression analysis in the presence of multicollinearity and outlier contamination.

Keywords: Poisson, Regression, Outlier, Multicollinearity, Estimate,

#### INTRODUCTION

Count data frequently arise in fields such as epidemiology, econometrics, and engineering. One of the most commonly employed methods for modeling such data is the Poisson regression model (PRM), which assumes that the conditional mean and variance of the response variable are equal. Despite its theoretical appeal, the practical application of the PRM is often hampered by two prominent challenges: outliers and multicollinearity.

Outliers, which are observations that deviate markedly from the general pattern of the data, can severely distort maximum likelihood estimates, reduce model efficiency, and yield misleading inferential results. Conversely, multicollinearity a condition where predictor variables are highly correlated inflates the variance of coefficient estimates, leading to instability and unreliable inference (Cantoni & Ronchetti, 2001; Hall & Shen, 2010)

To address these issues, various statistical techniques have been proposed. Robust regression methods are commonly employed to mitigate the influence of outliers (Chen *et al.*, 2014; Marazzi, 2021), whereas biased estimation techniques, such as ridge and Liu-type estimators, are often used to alleviate multicollinearity (Månsson & Shukur, 2011; Lukman *et al.*, 2021). However, most existing methods focus on resolving either outliers or multicollinearity in isolation. In practice, datasets often suffer from both problems simultaneously, diminishing the effectiveness of methods designed to handle only one issue (Abonazel & Saber, 2020; Dawoud & Abonazel, 2022).

To bridge this methodological gap, several robust Poisson estimators have been introduced. Notable examples include those proposed by Cantoni and Ronchetti (2001), Hall and Shen (2010), Chen et al. (2014, 2018), Hosseinian and Morgenthaler (2011), and Abonazel and Saber (2020). Among them, the robust Poisson estimator by Hosseinian and Morgenthaler (2011) based on the weighted maximum likelihood method (WMLM) has gained significant traction for its efficacy in

managing outliers in the response variable. However, integrated solutions that can effectively tackle both outliers and multicollinearity in the PRM are still scarce. Although some attempts have been made such as the Robust Poisson Ridge Regression (RPRR) estimator more comprehensive and efficient techniques are needed (Abonazel *et al.*, 2022). This motivates the current study, which introduces novel robust Poisson two-parameter estimators designed specifically to handle both multicollinearity and outliers simultaneously. These estimators are evaluated using theoretical analysis and simulation studies

## **METHODOLOGY**

The Poisson regression model (PRM) is a standard framework for analyzing count data, assuming the response variable  $(Y_i)$  follows a Poisson distribution with mean  $\mu_i(\beta) = \exp(X_i\beta)$  where  $X_i$  denotes the i-th observation in the design matrix and  $\beta$  is a vector of unknown parameters. Estimation of these parameters is typically carried out using the Pseudo-Maximum Likelihood (PML) method, operationalized through the Iteratively Reweighted Least Squares (IWLS) algorithm. This approach ensures consistent and asymptotically efficient parameter estimates under the standard assumptions of the Poisson model. The PML estimator is defined as:

$$\beta_{_{PMJE}} = (J)^{-1} X^{T} W s \tag{1}$$

Where  $J=X^TWX$ , s is an n - dimensional vector with the ith element  $s=\log\hat{\mu}_i+\frac{\left(y_i-\hat{\mu}_i\right)}{\hat{\mu}_i}$  and  $\hat{W}=diag\left[\hat{\mu}_i\right]$ . The MLE is asymptotically normally distributed, with its covariance matrix derived from the inverse of the observed information matrix, which corresponds to the negative second derivative of the log-likelihood function and expressed as:

$$Cov(\hat{\beta}_{PMLE}) = \left[ -E\left(\frac{\partial l}{\partial \beta_j \partial \beta_j^T}\right) \right]^{-1} = J^{-1}$$
(2)

The mean square error can calculated as follows:

$$MSE\left(\hat{\beta}_{PMLE}\right) = \sum_{i=1}^{p} \frac{1}{\lambda_i} \tag{3}$$

Where  $\lambda_i$  is the ith eigen value of the matrix J. The robust Poisson estimator by Hosseinian and Morgenthaler (2011) based on the weighted maximum likelihood method (WMLM) has gained significant traction for its efficacy in managing outliers in the response variable (y). The weighted function  $(W^*)$  of the WMLM depends on  $\mu_i$  and two constants (c1 and c2):

$$W^* = \begin{cases} 1if \frac{m}{c_1} < \mu_i < c_1 m; \\ \frac{c_1 \mu_i}{m} if \mu_i < \frac{m}{c_1}; \\ 0 \quad otherwise \end{cases}$$

. Where m is known as the median of  $\mu_i, c_1 = 2$  and  $c_2 = 3$  . Then, the WMLM estimation is defined as:

$$\sum_{i=1}^{n} \frac{\mu_{i}'}{\mu_{i}} W^{*} \left( y_{i} - \mu_{i} \right) x_{i} = 0 \tag{4}$$

A Robust Poisson maximum likelihood (RPML) estimator can be obtained by applying the Newton–Raphson algorithm to the system of equations in Equation (4). For further methodological details, refer to Hosseinian (2009) and Hosseinian and Morgenthaler (2011). Then, the RPML estimator by Abonazel *et al* (2022) is defined as:

$$\hat{\beta}_{RPMLE} = \left(\mathcal{F}\right)^{-1} X^T \hat{W}^* \hat{s}^*, \tag{5}$$

Where  $\mathcal{J} = X^T \hat{W}^* X$ , s is an n – dimensional vector with the ith element

$$\hat{s}^* = \log \hat{\mu}_i^* + \frac{\left(y_i^* - \hat{\mu}_i^*\right)}{\hat{\mu}_i^*}$$
 and  $\hat{W}^* = diag\left[\hat{\mu}_i^*\right]$ . The RPMLE follows, with its covariance matrix

defined as the inverse of the observed information matrix, derived from the second derivative of the log-likelihood function.

$$Cov(\hat{\beta}_{RPMLE}) = \left[ -E\left(\frac{\partial l}{\partial \beta_j \partial \beta_j^T}\right) \right]^{-1} = \mathcal{F}^{*-1}$$
(6)

The mean square error can calculated as follows:

$$MSE\left(\hat{\beta}_{RPMLE}\right) = \sum_{i=1}^{p} \frac{1}{\lambda_i^*} \tag{7}$$

Where  $\gamma^*$  and  $\lambda_j^*$  are the eigenvectors and Eigen values of  $\mathcal F$ , where  $\mathcal F = \gamma^* \Lambda^* \gamma^*$  with  $\Lambda^* = diag\left(\lambda_j^*\right)$ 

## **Robust Poisson Ridge Regression**

In a recent contribution, Abonazel and Dawoud (2022) introduced the Robust Poisson Ridge Regression (RPRR) estimator, designed to concurrently address the issues of outliers and multicollinearity within the Poisson Regression Model (PRM). The formulation of the RPRR estimator is defined as follows:

$$\hat{\beta}_{RPRR} = \left(\mathcal{F} + kI\right)^{-1} X^T \hat{W}^* \hat{s}^* \tag{8}$$

And the MSE of the RPRR is:

$$MSE(\hat{\beta}_{PRRE}) = \sum_{i=1}^{p+1} \frac{\lambda_i^*}{(\lambda_i^* + k)^2} + \sum_{i=1}^{p} \frac{k^2 \hat{\alpha}_i^{*2}}{(\lambda_i^* + k)^2}$$
(9)

#### **Robust Poisson Liu Regression**

In a recent study, Dawoud *et al.* (2022) developed the Robust Poisson Ridge Regression (RPL) estimator, which is specifically designed to simultaneously mitigate the effects of outliers and multicollinearity within the Poisson Regression Model (PRM). The RPRR estimator is formally expressed as:

$$\hat{\beta}_{RPL} = (\mathcal{F} + I)^{-1} (\mathcal{F} + dI) \hat{\beta}_{RPMLE} \tag{10}$$

And the MSE of the RPL is:

$$MSE(\hat{\beta}_{PRRE}) = \sum_{i=1}^{p+1} \frac{\left(\lambda_{i}^{*} + d\right)}{\lambda_{i}^{*} \left(\lambda_{i}^{*} + 1\right)^{2}} + \left(1 - d\right)^{2} \sum_{i=1}^{p+1} \frac{\hat{\alpha}_{i}^{*2}}{\left(\lambda_{i}^{*} + 1\right)^{2}}$$
(11)

## **Robust Poisson Kibra Lukman Regression**

Dawoud et al. (2022) recently introduced the Robust Poisson K-L Ridge (RPKL) estimator as a methodological advancement aimed at addressing the dual challenges of outliers and multicollinearity within the Poisson Regression Model (PRM). The formulation of the RPKL estimator is given by:

$$\hat{\beta}_{RPKL} = (\mathcal{F} + kI)^{-1} (\mathcal{F} - kI) \hat{\beta}_{RPMLE} \tag{12}$$

And the MSE of the RPKL is:

$$MSE(\hat{\beta}_{PRKL}) = \sum_{i=1}^{p+1} \frac{\left(\lambda_{i}^{*} - k\right)}{\lambda_{i}^{*} \left(\lambda_{i}^{*} + k\right)^{2}} + 4k^{2} \sum_{i=1}^{p+1} \frac{\hat{\alpha}_{i}^{*2}}{\left(\lambda_{i}^{*} + k\right)^{2}}$$
(13)

## The proposed estimator

Given that the PL, PKL, and PMKL estimators have demonstrated greater efficiency than the Poisson ridge regression (PRR) estimator within the Poisson regression framework (PRM), robust counterparts of these estimators have been developed to address both multicollinearity and the

presence of outliers, thereby extending one-parameter methods to more resilient alternatives. Recently, Albert *et al.* (2025) introduced a novel two-parameter estimator within the PRM context, which has shown superior performance compared to existing estimators such as PMLE, PRR, PL, and PKL. Building on this advancement, we propose an extension of this two-parameter approach to simultaneously address multicollinearity and outlier influence. The resulting estimator, denoted as RProp1, is formally defined as follows:

$$\hat{\beta}_{RProp1} = (\mathcal{F} + I)^{-1} (\mathcal{F} + dI) (\mathcal{F} + kI)^{-1} (\mathcal{F} - kI) \hat{\beta}_{RPMLE}$$
(14)

And the MSE of the RProp1 is:

$$MSE(\hat{\beta}_{RProp1}) = \sum_{i=1}^{p} \left[ \frac{\left(\lambda_{i}^{*} - k\right)^{2} \left(\lambda_{i}^{*} + d\right)^{2}}{\lambda_{i}^{*} \left(\lambda_{i}^{*} + I\right)^{2} \left(\lambda_{i}^{*} + k\right)^{2}} \right] + \sum_{i=1}^{p} \left[ \frac{\left(\left(2k + 1 - d\right)\lambda_{i}^{*} + k\left(d + 1\right)\right)^{2}}{\left(\lambda_{i}^{*} + I\right)^{2} \left(\lambda_{i}^{*} + k\right)^{2}} \right] \hat{\alpha}_{i}^{*2}$$
(15)

# **Superiority of Proposed Estimators**

**Lemma:** Suppose that  $\alpha_i = M_i y, i = 1,2$  be the two competing estimators of  $\alpha$ . Assume that  $I = Cov(\hat{\alpha}_1) - Cov(\hat{\alpha}_2) > 0$ , then,  $MSEM(\hat{\alpha}_1) - MSEM(\hat{\alpha}_2) > 0$  if and only if  $v_2(I + v_1v_1) \le 1$ , where  $v_i$  denotes the bias of  $\hat{\alpha}_i$ , according to Trenkler and Toutenburg (1990).

The mean square error matrix (MSEM) of an estimator  $\hat{\beta}$  is defined as

MSEM 
$$(\hat{\beta}) = Cov(\hat{\beta}) + bias(\hat{\beta})bias(\hat{\beta})$$

$$MSEM(\hat{\beta}) = Cov(\hat{\beta}) + bias(\hat{\beta})bias(\hat{\beta})'$$

Where  $Cov(\hat{\beta})$  is the dispersion matrix and  $bias(\hat{\beta}) = E(\hat{\beta}) - \beta$ 

The bias and dispersion matrix of  $\hat{\alpha}_{prop1}$  can be computed as follows:

$$Bias(\hat{\beta}_{Rprop1}) = \left[ \left( \Lambda^* + 1 \right)^{-1} \left( \Lambda^* + dI \right) \left( \Lambda^* + kI \right)^{-1} \left( \Lambda^* - kI \right) - I \right] \alpha^*$$
(16)

$$Cov(\hat{\beta}_{Rprop1}) = (\Lambda^* + 1)^{-1} (\Lambda^* + dI) (\Lambda^* + kI)^{-1} (\Lambda^* - kI) \Lambda^{*-1} (\Lambda^* + 1)^{-1} (\Lambda^* + dI) (\Lambda^* + kI)^{-1} (\Lambda^* - kI)$$
(17)

The MSEM and MSE in terms of eigenvalues are defined respectively as

$$MSEM(\hat{\beta}_{Rprop1}) = Cov(\hat{\beta}_{Rprop1}) + Bias(\hat{\beta}_{Rprop1})Bias(\hat{\beta}_{Rprop1})$$

$$(\Lambda^* + 1)^{-1} (\Lambda^* + dI) (\Lambda^* + kI)^{-1} (\Lambda^* - kI) \Lambda^{*-1} (\Lambda^* + 1)^{-1} (\Lambda^* + dI) (\Lambda^* + kI)^{-1} (\Lambda^* - kI) +$$

$$= \left[ (\Lambda^* + 1)^{-1} (\Lambda^* + dI) (\Lambda^* + kI)^{-1} (\Lambda^* - kI) - I \right] \alpha^* \alpha^* \left[ (\Lambda^* + 1)^{-1} (\Lambda^* + dI) (\Lambda^* + kI)^{-1} (\Lambda^* - kI) - I \right]$$

$$(18)$$

$$MSE(\hat{\beta}_{Rprop1}) = tr(MSEM(\hat{\beta}_{Rprop1}))$$

$$MSE(\hat{\beta}_{Rprop1}) = \sum_{i=1}^{p+1} \left[ \frac{\left(\lambda_{i}^{*} - k\right)^{2} \left(\lambda_{i}^{*} + d\right)^{2}}{\lambda_{i}^{*} \left(\lambda_{i}^{*} + I\right)^{2} \left(\lambda_{i}^{*} + k\right)^{2}} \right] + \sum_{i=1}^{p} \left[ \frac{\left(\left(2k + 1 - d\right)\lambda_{i}^{*} + k\left(d + 1\right)\right)^{2}}{\left(\lambda_{i}^{*} + I\right)^{2} \left(\lambda_{i}^{*} + k\right)^{2}} \right] \alpha_{i}^{*2}$$
(19)

Comparison of  $\hat{lpha}_{\mathit{Rprop1}}$  and  $\hat{lpha}_{\mathit{RPMLE}}$ 

$$\hat{\beta}_{RPMLE} = \Lambda^{-1} Q^T X^T \hat{W}^* \hat{s}^* \text{ with } MSEM \left( \hat{\beta}_{RPMLE} \right) = \Lambda^{-1}$$

**Theorem 1**:  $\hat{\beta}_{Rprop1}$  is better than  $\hat{\beta}_{RPMLE}$  if

$$\alpha' \left( \left( \Lambda^* + 1 \right)^{-1} \left( \Lambda^* + dI \right) \left( \Lambda^* + kI \right)^{-1} \left( \Lambda^* - kI \right) - I \right)' \left[ \left( \Lambda^{*-1} - \left( \Lambda^* + 1 \right)^{-2} \left( \Lambda^* + dI \right)^2 \left( \Lambda^* + kI \right)^{-2} \left( \Lambda^* - kI \right)^2 \right) \right]^{-1} \left( \left( \Lambda^* + 1 \right)^{-1} \left( \Lambda^* + dI \right) \left( \Lambda^* + kI \right)^{-1} \left( \Lambda^* - kI \right) - I \right) \alpha^* < 1$$

**Proof** 

The difference of the dispersion is

$$Cov\left(\hat{\beta}_{RPMLE}\right) - Cov\left(\hat{\beta}_{Rprop1}\right) = Q\left(\Lambda^{*-1} - \Lambda^{*-1}\left(\Lambda^{*} + 1\right)^{-2}\left(\Lambda^{*} + dI\right)^{2}\left(\Lambda^{*} + kI\right)^{-2}\left(\Lambda^{*} - kI\right)^{2}\right)Q^{T}$$

$$=Qdiag\left[\frac{1}{\lambda_{i}^{*}}-\frac{\left(\lambda_{i}^{*}-k\right)^{2}\left(\lambda_{i}^{*}+d\right)^{2}}{\lambda_{i}^{*}\left(\lambda_{i}^{*}+1\right)^{2}\left(\lambda_{i}^{*}+k\right)^{2}}\right]_{i=1}^{p}Q^{T}$$
(20)

It is observed that  $\left(\Lambda^{*-1} - \Lambda^{*-1} \left(\Lambda^* + 1\right)^{-2} \left(\Lambda^* + dI\right)^2 \left(\Lambda^* + kI\right)^{-2} \left(\Lambda^* - kI\right)^2\right)$  is positive definite since

for 0 < d < 1 and k > 0,  $\lambda_i^* \left(\lambda_i + 1\right)^2 \left(\lambda_i^* + k\right)^2 - \lambda_i^* \left(\lambda_i^* - k\right)^2 \left(\lambda_i^* + d\right)^2 > 0$ . Hence, by lemma the proof is completed.

**Theorem 2**:  $\hat{\beta}_{Rprop1}$  is better than  $\hat{\beta}_{RPRRE}$  if

$$\alpha^{*'}\left(\left(\Lambda^{*}+1\right)^{-1}\left(\Lambda^{*}+dI\right)\left(\Lambda^{*}+kI\right)^{-1}\left(\Lambda^{*}-kI\right)-I\right)^{'}\left[J_{1}+\left(\left(\Lambda^{*}+k\right)^{-1}-I\right)\alpha^{*}\alpha^{*'}\left(\left(\Lambda^{*}+k\right)^{-1}-I\right)\right]^{-1}\left(\left(\Lambda^{*}+I\right)^{-1}\left(\Lambda^{*}+dI\right)\left(\Lambda^{*}+kI\right)^{-1}\left(\Lambda^{*}-kI\right)-I\right)\alpha^{*}<1$$

$$J_{1} = Q \left( \Lambda^{*} \left( \Lambda^{*} + k \right)^{-2} - \Lambda^{*-1} \left( \Lambda^{*} + 1 \right)^{-2} \left( \Lambda^{*} + dI \right)^{2} \left( \Lambda^{*} + kI \right)^{-2} \left( \Lambda^{*} - kI \right)^{2} \right) Q^{T}$$

Proof

The difference of the dispersion is

$$Cov\left(\hat{\beta}_{RPRRE}\right) - Cov\left(\hat{\beta}_{Rprop1}\right) = Q\left(\Lambda^*\left(\Lambda^* + k\right)^{-2} - \Lambda^{*-1}\left(\Lambda^* + 1\right)^{-2}\left(\Lambda^* + dI\right)^2\left(\Lambda^* + kI\right)^{-2}\left(\Lambda^* - kI\right)^2\right)Q^T$$

$$=Qdiag\left[\frac{\lambda_{i}^{*}}{\left(\lambda_{i}^{*}+k\right)^{2}}-\frac{\left(\lambda_{i}^{*}-k\right)^{2}\left(\lambda_{i}^{*}+d\right)^{2}}{\lambda_{i}^{*}\left(\lambda_{i}^{*}+1\right)^{2}\left(\lambda_{i}^{*}+k\right)^{2}}\right]_{i=1}^{p}Q^{T}$$
(21)

It is observed that  $\left(\Lambda^* \left(\Lambda^* + k\right)^{-2} - \Lambda^{*-1} \left(\Lambda^* + 1\right)^{-2} \left(\Lambda^* + dI\right)^2 \left(\Lambda^* + kI\right)^{-2} \left(\Lambda^* - kI\right)^2\right)$  will be positive

definite if and only if  $\lambda_i^{*2} \left(\lambda_i^* + 1\right)^2 - \left(\lambda_i^* - k\right)^2 \left(\lambda_i^* + d\right)^2 > 0$ . For 0 < d < 1 and k > 0, by lemma 3 the proof is completed.

**Theorem 3**:  $\hat{\alpha}_{Rprop1}$  is better than  $\hat{\alpha}_{RPLE}$  if

$$\alpha^{*'} \Big( \left( \Lambda^* + 1 \right)^{-1} \left( \Lambda^* + dI \right) \left( \Lambda^* + kI \right)^{-1} \left( \Lambda^* - kI \right) - I \Big) \Big[ J_2 + \left( \left( \Lambda^* + 1 \right)^{-1} \left( \Lambda^* + d \right) - I \right) \alpha \alpha' \Big( \left( \Lambda^* + 1 \right)^{-1} \left( \Lambda^* + dI \right) - I \Big) \Big]^{-1} \Big[ \left( \Lambda^* + I \right)^{-1} \left( \Lambda^* + dI \right) \left( \Lambda^* + kI \right)^{-1} \left( \Lambda^* - kI \right) - I \Big) \alpha^* < 1$$

$$J_{2} = Q \left( \Lambda^{*-1} \left( \Lambda^{*} + d \right)^{2} \left( \Lambda^{*} + 1 \right)^{-2} - \Lambda^{*-1} \left( \Lambda^{*} + 1 \right)^{-2} \left( \Lambda^{*} + dI \right)^{2} \left( \Lambda^{*} + kI \right)^{-2} \left( \Lambda^{*} - kI \right)^{2} \right) Q^{T}$$

Proof

The difference of the dispersion is

$$Cov(\hat{\beta}_{RPLE}) - Cov(\hat{\beta}_{Rprop1}) = Q(\Lambda^{*-1}(\Lambda^* + d)^2(\Lambda^* + 1)^{-2} - \Lambda^{*-1}(\Lambda^* + 1)^{-2}(\Lambda^* + dI)^2(\Lambda^* + kI)^{-2}(\Lambda^* - kI)^2)Q^T$$

$$=Qdiag\left[\frac{\left(\lambda_{i}^{*}+d\right)^{2}}{\lambda_{i}^{*}\left(\lambda_{i}^{*}+1\right)^{2}}-\frac{\left(\lambda_{i}^{*}-k\right)^{2}\left(\lambda_{i}^{*}+d\right)^{2}}{\lambda_{i}^{*}\left(\lambda_{i}^{*}+1\right)^{2}\left(\lambda_{i}^{*}+k\right)^{2}}\right]_{i=1}^{p}Q^{T}$$
(22)

$$\Lambda^{*-1} \left( \Lambda^* + d \right)^2 \left( \Lambda^* + 1 \right)^{-2} - \Lambda^{*-1} \left( \Lambda^* + 1 \right)^{-2} \left( \Lambda^* + dI \right)^2 \left( \Lambda^* + kI \right)^{-2} \left( \Lambda^* - kI \right)^2$$
 will be positive definite

if and only if  $(\lambda_i^* + k)^2 - (\lambda_i^* - k)^2 > 0$  for k > 0 and 0 < d < 1. Hence, by lemma the proof is completed.

**Theorem 4**:  $\hat{\alpha}_{Rprop1}$  is better than  $\hat{\alpha}_{PKLE}$  if

$$\alpha^{*'}\left(\left(\Lambda^{*}+1\right)^{-1}\left(\Lambda^{*}+dI\right)\left(\Lambda^{*}+kI\right)^{-1}\left(\Lambda^{*}-kI\right)-I\right)\left[J_{3}+\left(\left(\Lambda^{*}+k\right)^{-1}\left(\Lambda^{*}-k\right)-I\right)\alpha\alpha^{'}\left(\left(\Lambda^{*}+k\right)^{-1}\left(\Lambda^{*}-k\right)-I\right)\right]^{-1}\left(\left(\Lambda^{*}+l\right)^{-1}\left(\Lambda^{*}+dI\right)\left(\Lambda^{*}+kI\right)^{-1}\left(\Lambda^{*}-kI\right)-I\right)\alpha<1$$

$$J_{3} = Q \left( \Lambda^{*-1} \left( \Lambda^{*} - k \right)^{2} \left( \Lambda^{*} + k \right)^{-2} - \Lambda^{*-1} \left( \Lambda^{*} + 1 \right)^{-2} \left( \Lambda^{*} + dI \right)^{2} \left( \Lambda^{*} + kI \right)^{-2} \left( \Lambda^{*} - kI \right)^{2} \right) Q^{T}$$

Proof

The difference of the dispersion is

$$Cov(\hat{\beta}_{RPKLE}) - Cov(\hat{\beta}_{Rprop1}) = Q(\Lambda^{*-1}(\Lambda^* - k)^2(\Lambda^* + k)^{-2} - \Lambda^{*-1}(\Lambda^* + 1)^{-2}(\Lambda^* + dI)^2(\Lambda^* + kI)^{-2}(\Lambda^* - kI)^2)Q^{T} - Q(\Lambda^* - kI)^2(\Lambda^* - kI)^2$$

$$=Qdiag\left[\frac{\left(\lambda_{i}^{*}-k\right)^{2}}{\lambda_{i}^{*}\left(\lambda_{i}^{*}+k\right)^{2}}-\frac{\left(\lambda_{i}^{*}-k\right)^{2}\left(\lambda_{i}^{*}+d\right)^{2}}{\lambda_{i}^{*}\left(\lambda_{i}^{*}+1\right)^{2}\left(\lambda_{i}^{*}+k\right)^{2}}\right]_{i=1}^{p}Q^{T}$$
(23)

$$\Lambda^{*-1} \left( \Lambda^* - k \right)^2 \left( \Lambda^* + k \right)^{-2} - \Lambda^{*-1} \left( \Lambda^* + 1 \right)^{-2} \left( \Lambda^* + dI \right)^2 \left( \Lambda^* + kI \right)^{-2} \left( \Lambda^* - kI \right)^2 \text{ will be positive definite}$$

if and only if  $(\lambda_i^* + 1)^2 - (\lambda_i^* + d)^2 > 0$  for k > 0 and 0 < d < 1. Hence, by lemma the proof is completed.

Selection of biasing parameters k and d for  $\ \hat{eta}_{\it Rprop1}$ 

$$_{\text{MSE}}(\alpha(k,d)) = E[(\hat{\alpha}(k,d) - \alpha)'(\alpha(k,d) - \alpha)]$$

$$g(k,d) = MSE(\hat{\alpha}(k,d)) = tr[MSEM(\hat{\alpha}(k,d))]$$

$$MSE\left(\hat{\beta}_{Rprop1}\right) = \sum_{i=1}^{p} \left[ \frac{\left(\lambda_{i}^{*} - k\right)^{2} \left(\lambda_{i}^{*} + d\right)^{2}}{\lambda_{i}^{*} \left(\lambda_{i}^{*} + I\right)^{2} \left(\lambda_{i}^{*} + k\right)^{2}} \right] + \sum_{i=1}^{p} \left[ \frac{\left(\left(2k + 1 - d\right)\lambda_{i}^{*} + k\left(d + 1\right)\right)^{2}}{\left(\lambda_{i}^{*} + I\right)^{2} \left(\lambda_{i}^{*} + k\right)^{2}} \right] \alpha_{i}^{*2}$$

Considering d to be fixed, an optimal value of k is the value that minimizes  $MSE(\hat{\beta}_{Rprop1})$ .

Then, by differentiating g(k, d) w.r.t. k and equating to 0, we have

$$k = \frac{\lambda_i^* \left(\lambda_i^* + d\right) + \left(d - 1\right) \lambda_i^{*2} \alpha_i^{*2}}{\left(\lambda_i^* + d\right) + \lambda_i^* \left(2\lambda_i^* + d + 1\right) \alpha_i^{*2}}$$
(24)

However, k depends on the unknown  $\alpha_i$ . For practical purposes, it will be replaced by its unbiased estimator  $\hat{\alpha}_i$ . Hence, this will be obtained

$$\hat{k} = \frac{\lambda_{i}^{*} (\lambda_{i}^{*} + d) + (d - 1) \lambda_{i}^{*2} \hat{\alpha}_{i}^{*2}}{(\lambda_{i}^{*} + d) + \lambda_{i}^{*} (2\lambda_{i}^{*} + d + 1) \hat{\alpha}_{i}^{*2}}$$

Equation (24) returns the biasing parameter for the PKL estimator when d =1, which is defined as follows:

$$\hat{k} = \frac{\lambda_i^*}{1 + 2\lambda_{i,i}^* \hat{\alpha}_i^{*2}}$$

Building upon the foundational contributions of Kibra (2003), Lukman and Ayinde (2017), as well as Oladapo *et al.* (2022, 2024), the conceptual frameworks presented in their studies have been adapted to inform the development of the proposed estimator. Consequently, the corresponding shrinkage parameters considered in this study are defined as follows:

$$\hat{k}_{HM} = p \sum_{i=1}^{p} \left( \frac{\lambda_{i}^{*} (\lambda_{i}^{*} + d) + (d-1) \lambda_{i}^{*2} \hat{\alpha}_{i}^{*2}}{(\lambda_{i}^{*} + d) + \lambda_{i}^{*} (2\lambda_{i}^{*} + d + 1) \hat{\alpha}_{i}^{*2}} \right)$$
(25)

$$\hat{k}_{MED} = Median \left( \frac{\lambda_i^* \left( \lambda_i^* + d \right) + \left( d - 1 \right) \lambda_i^{*2} \hat{\alpha}_i^{*2}}{\left( \lambda_i^* + d \right) + \lambda_i^* \left( 2 \lambda_i^* + d + 1 \right) \hat{\alpha}_i^{*2}} \right)$$

$$(26)$$

## **Simulation Experiment**

**Simulation Design**: Recognizing the limitations of relying solely on theoretical analysis to assess estimator performance, a detailed Monte Carlo simulation study was implemented. The response variable was drawn from a Poisson distribution defined as  $Y_i \sim Poisson(\mu_i)$ , where  $\mu_i = \exp(X_i\beta)$ , i=1,2,...,n,  $\beta=(\beta_0,\beta_1,\beta_2,...,\beta_P)$ , and represent model parameters. Here,  $X_{ith}$  denotes the ith row of the design matrix X. In line with the approaches used by Kibra (2003), Oladapo *et al.* (2023), and Owolabi *et al.* (2022), the explanatory variables in X were generated using the following procedure:

$$x_{ij} = (1 - rho^2)^{\frac{1}{2}} z_{ij} + rhoz_{ip+1}, i = 1, 2, ..., n, j = 1, 2, ..., p.$$
(27)

where rho  $(\rho^2)$  is the correlation between the explanatory variables. The values of  $\rho$  are chosen to be 0.8, 0.9, 0.95 and 0.99. The mean function is obtained for p=2, 4, 10 and 12 regressors, respectively. The slope coefficients chosen so that  $\sum_{j}^{p} \beta_{j}^{2} = 1$  and  $\beta_{1} = \beta_{2} = ... = \beta_{p}$  for sample sizes 200,400,600,800 and 1000. Some outliers were generated with different percentages ( $\tau = 0\%$ , 10%, and 20%) in the model by randomly replacing some values due to the selected percentage  $\tau$ % from the response variable. Point of outliers;  $Y_{i(Outlier)} = f * Max(Y_i) + Y_i$ , where magnitude of outliers in the y-direction (f) and percentage of outliers in the y-direction ( $\tau$ ). Simulation experiment conducted through R programming language.

The Mean Squared Error (MSE) for each estimator is computed as follows:

$$MSE(\beta^*) = \frac{1}{1000} \sum_{i=1}^{1000} (\beta_i^* - \beta)' (\beta_i^* - \beta)$$
 (28)

Here  $\beta_i^*$ , denotes the vector of predicted values obtained from the ith simulation run using one of the evaluated estimators namely PMLE, PRRE, PLE, PKLE, and PMTPLE. Among these, the estimator yielding the smallest MSE is regarded as the most effective.

#### **Simulation Results**

Table 1 reports the Mean Squared Error (MSE) of several estimators under various simulation settings characterized by different intercept values, sample sizes (n = 200, 300, 400), and levels of multicollinearity ( $\rho$  = 0.8, 0.9, 0.95, 0.99), with 20% contamination ( $\tau$  = 20%) and two predictors (P = 2). Across all scenarios, the Robust Poisson Maximum Likelihood Estimator (RPMLE) consistently produced the highest MSE values, confirming its sensitivity to both multicollinearity and outlier contamination. In contrast, RPR, RPL, and RPKL estimators significantly outperformed RPMLE, with notably lower MSEs across all configurations.

Among all the estimators, the proposed methods particularly prop1HM demonstrated the most robust and stable performance. Prop1HM frequently yielded the lowest MSE values, especially at higher correlation levels ( $\rho \geq 0.95$ ) and larger sample sizes. This suggests a high degree of robustness and efficiency in the presence of multicollinearity and contamination. While increasing the correlation among predictors generally led to higher MSEs for most estimators, the proposed methods remained resilient, showing minimal performance degradation. Additionally, increasing the sample size led to a general reduction in MSE for all methods, with the largest improvements observed in the robust and proposed estimators.

Overall, the findings indicate that the proposed estimators, particularly prop1HM, offer substantial improvements in estimation accuracy over traditional methods under challenging data conditions, including high multicollinearity and data contamination with outliers.

Table 1: MSE of different estimators when  $\tau$ =20% and P = 2

interce								prop1M	prop1H
pt	n	rho	RPML	RPR	RPL	RPK-L	prop1	Е	М
		0.8	4.0264	0.6908	0.7091	0.7013	0.7091	0.7269	1.6191
		0.9	4.1941	0.7024	0.7124	0.7106	0.7124	0.7363	1.5745
		0.95	4.2060	0.7305	0.7308	0.7357	0.7308	0.7504	1.9863
	200	0.99	4.5897	0.9382	0.8871	0.9273	0.8871	0.8704	2.8476
		0.8	4.2628	0.6825	0.6856	0.6882	0.6856	0.7077	1.3076
-1		0.9	4.4382	0.6914	0.6775	0.6950	0.6775	0.7126	1.2702
-1		0.95	4.6848	0.7430	0.6687	0.7442	0.6687	0.7293	1.4628
	300	0.99	6.0073	1.2024	0.7356	1.1878	0.7356	0.7800	1.5890
		0.8	3.8199	0.6465	0.6518	0.6524	0.6518	0.6646	1.0581
		0.9	3.9811	0.6343	0.6363	0.6391	0.6363	0.6503	1.0115
		0.95	4.1237	0.6388	0.6266	0.6422	0.6266	0.6454	0.9906
	400	0.99	4.6541	0.7936	0.6503	0.7888	0.6503	0.6489	0.9998
		0.8	3.0391	0.2472	0.2468	0.2470	0.2468	0.2468	0.2452
		0.9	3.1428	0.2560	0.2546	0.2556	0.2546	0.2547	0.2457
0		0.95	3.1589	0.2698	0.2641	0.2689	0.2641	0.2649	0.2419
U	200	0.99	3.2618	0.3836	0.3012	0.3769	0.3012	0.2749	0.2626
		0.8	3.0586	0.2440	0.2435	0.2438	0.2435	0.2434	0.2386
	300	0.9	3.0492	0.2495	0.2476	0.2491	0.2476	0.2477	0.2343

		0.95	3.1515	0.2726	0.2622	0.2716	0.2622	0.2656	0.2247
		0.99	3.5738	0.4928	0.2533	0.4863	0.2533	0.2937	0.2489
		0.8	2.7329	0.2204	0.2202	0.2203	0.2202	0.2202	0.2193
		0.9	2.8863	0.2153	0.2149	0.2152	0.2149	0.2149	0.2109
		0.95	3.0574	0.2194	0.2178	0.2190	0.2178	0.2178	0.2067
	400	0.99	3.1996	0.2859	0.2360	0.2831	0.2360	0.2427	0.2270
		0.8	6.0140	0.0932	0.0913	0.0930	0.0913	0.0914	0.0839
		0.9	5.8138	0.0957	0.0937	0.0955	0.0937	0.0939	0.0856
		0.95	5.7914	0.1020	0.0996	0.1018	0.0996	0.1001	0.0894
	200	0.99	6.1245	0.1497	0.1276	0.1482	0.1276	0.1443	0.0816
				0.0891	0.0879	0.0889	0.0879		
1		0.8	5.7674	0	9	6	9	0.08797	0.0826
		0.9	6.0084	0.0908	0.0896	0.0906	0.0896	0.0897	0.0836
1		0.95	6.4139	0.1022	0.1003	0.1020	0.1003	0.1009	0.0916
	300	0.99	6.2366	0.1939	0.1435	0.1920	0.1435	0.1886	0.0865
				0.0785	0.0776	0.0784	0.0776		
		0.8	6.0934	3	8	3	8	0.07771	0.0740
		0.9	6.2382	0.0767	0.0759	0.0766	0.0759	0.0759	0.0722
		0.95	5.9348	0.0778	0.0768	0.0777	0.0768	0.0770	0.0727
	400	0.99	5.8016	0.1039	0.0975	0.1035	0.0975	0.1020	0.0801

The MSE that is smallest is bold

Table 2 presents the mean squared error (MSE) performance of various logistic regression estimators under 20% contamination and four predictors. Across all configurations, the RPMLE consistently exhibits the highest MSE, highlighting its vulnerability to both multicollinearity and data contamination. Classical shrinkage-based alternatives such as RPR, RPL, and RPK-L estimators offer modest improvements over RPMLE, yet their MSEs increase markedly under stronger multicollinearity ( $\rho \ge 0.95$ ) and larger sample sizes. In contrast, the proposed estimators (prop1, prop1ME, and especially prop1HM) demonstrate superior performance across all simulation settings. Notably, prop1HM achieves the lowest or near-lowest MSE values in nearly all scenarios, particularly excelling under severe multicollinearity ( $\rho = 0.99$ ) and small to moderate sample sizes (n = 200–400). Even as the intercept value changes from -1 to 1, the ranking of estimator performance remains consistent, with the proposed estimators retaining their edge. The

stability and robustness of prop1HM even in high-dimensional, noisy conditions underscore its practical advantage over traditional methods. These results affirm the effectiveness of the proposed methodology in mitigating the adverse effects of outlier contamination and multicollinearity in logistic regression.

Table 2: MSE of different estimators when  $\tau$ =20% and P = 4

	SE OI	umere	eni estimato	is when $\tau = 2$	20% and P =	- 4			
intercep								prop1M	prop1H
t	n	rho	RPML	RPRR	RPL	RPK-L	prop1	Е	M
		0.8	3.4667	0.5469	0.5811	0.5607	0.5811	0.5864	0.5745
		0.9	3.3149	0.5388	0.5596	0.5470	0.5596	0.5646	0.5587
		0.9							
		5	3.6570	0.5966	0.5733	0.5967	0.5733	0.5853	0.5833
	20	0.9							
	0	9	3.6014	1.3257	0.8113	1.2600	0.8113	0.7195	0.7845
		0.8	9.5276	9.8089	9.7487	9.8025	9.7487	9.7825	9.7924
		0.9	20.9870	28.8728	28.8300	28.8596	28.8300	28.8120	28.9870
-1		0.9							
-1		5	50.1574	63.9683	63.9141	63.9471	63.9141	63.8415	63.9365
	30	0.9	277.885	295.844	295.474	295.747	295.474		
	0	9	1	4	0	3	0	295.3904	295.4786
		0.8	3.5941	0.4090	0.4266	0.4176	0.4266	0.4268	1.2698
		0.9	3.3816	0.4105	0.4412	0.4167	0.4412	0.4244	1.3496
		0.9							
		5	3.5974	0.4998	0.6276	0.5021	0.6276	0.5057	1.8273
	40	0.9							
	0	9	5.5655	4.0942	3.8063	4.0698	3.8063	3.8226	1.9309
		0.8	2.9709	0.2399	0.2325	0.2387	0.2325	0.2363	0.1551
		0.9	9.2140	6.9268	6.5542	6.9244	6.5542	6.8652	4.8557
		0.9							
		5	31.3100	29.0709	28.2200	29.0635	28.2200	28.7831	17.3894
	20	0.9	181.346	179.264	158.284	179.218	158.284		
	0	9	7	4	0	7	0	175.3685	178.3064
		0.8	13.9722	17.9229	17.9203	17.9219	17.9203	17.9182	18.1054
0		0.9	34.7387	30.5778	30.5750	30.5767	30.5750	30.5705	31.3246
U		0.9							
		5	59.4891	53.8385	53.8312	53.8366	53.8312	53.8242	56.9313
	30	0.9	245.956	239.889	239.819	239.878	239.819		
	0	9	0	6	8	0	8	239.8150	240.1475
		0.8	2.8354	0.1448	0.1443	0.1445	0.1443	0.1443	0.1248
		0.9	3.1807	0.3408	0.3353	0.3404	0.3353	0.3386	0.1881
	40	0.9							
	0	5	3.9825	1.5793	1.5708	1.5782	1.5708	1.5569	0.5647

		0.9							
		9	37.0352	37.5041	36.5771	37.4978	36.5771	37.2338	20.0850
		0.8	17.8673	9.3570	9.3140	9.3565	9.3140	9.3557	8.7022
		0.9	32.7416	20.8962	20.8671	20.8957	20.8671	20.8954	19.2829
		0.9							
		5	41.6098	33.6252	33.5766	33.6242	33.5766	33.6239	28.8128
	20	0.9	129.544	117.581	116.670	117.576	116.670		
	0	9	1	6	4	0	4	117.5546	89.5307
		0.8	30.2117	18.7017	18.7016	18.7017	18.7016	18.7015	18.6991
		0.9	47.5881	26.7076	26.7075	26.7076	26.7075	26.7074	26.7035
1		0.9							
1		5	59.9399	36.1348	36.1344	36.1348	36.1344	36.1344	36.0830
	30	0.9	133.377	101.613	101.607	101.612	101.607		
	0	9	1	6	8	2	8	101.6109	100.8533
		0.8	6.9160	0.3041	0.2988	0.3040	0.2988	0.3034	0.2491
		0.9	18.6088	7.6656	7.6620	7.6654	7.6620	7.6628	7.2214
		0.9							
		5	29.9047	15.6965	15.6864	15.6964	15.6864	15.6949	15.4356
	40	0.9							
	0	9	55.2891	39.7585	39.7013	39.7577	39.7013	39.7554	39.6931

The MSE that is smallest is bold

## Conclusion

The simulation results provide compelling evidence that the proposed estimators particularly prop1HM offer significant improvements over conventional methods in the presence of outlier contamination and multicollinearity in Poisson regression models. While RPMLE and classical shrinkage estimators (RPR, RPL, RPK-L) show performance degradation under these adverse conditions, the proposed methods demonstrate greater robustness, stability, and efficiency. These findings highlight the practical utility of the proposed estimators, especially prop1HM, as reliable alternatives for real-world applications where data contamination and predictor correlation are common challenges.

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